## RA-3000 <br> Electric Actuator

## Introduction

The RA-3000 series synchronous motor-driven reversible actuators are available for 3-point (floating) or with electric positioner for 0... 10 V control. They feature factory calibrated pressure switches to provide specified close-off ratings.

These actuators are available in three sizes with $1600 \mathrm{~N}, 1800 \mathrm{~N}$ and with 3000 N nominal force and can be used with JC flanged valves according to maximum close-off pressure ratings specified.

Factory fitted options, such as $2 k \Omega$ feedback potentiometer, auxiliary switches and hand crank are available.


## RA-3000 Actuator with VG8000N valve

## Features and Benefits

- Uses synchronous motor with pressure switches
- Special clamp coupler quick-fit system
- Models for 3-point and proportional VDC control
- Positioner with adjustable starting point, span, and direct/reverse action
- Active 0... 10 VDC position feedback on proportional models

O Optional auxiliary switches and feedback potentiometer available

- Optional hand crank
$0 . .10$

Fixed close-off force
Constant running time
Provides quick and easy mounting of the actuator on valves with slotted stem. Cuts installation costs.
Allows optimum choice of control signal

Provides flexibility in application
Allows easy sequencing from only one output signal
Provides active signal for independent position monitoring

Provides potential free contacts for independent monitoring of the actuator's position

Allows manual positioning independent of power supply

*) For other supply voltage and frequency, please contact your Johnson Controls supplier.

## Ordering Procedure

The valves and actuators can be ordered separately or factory mounted. When factory mounted, please add " $+\mathbf{M}$ " behind the order code for the actuator.

## For example:

For a 2-way valve, DN 65, kvs 63, PN 16 plus actuator with electric positioner $0 \ldots 10 \mathrm{~V}$ input, 24 VAC / 50 Hz supply, order:

| Item 1 VG82G1S1N | (valve body) |
| :--- | :--- |
| Item 2 RA-3041-7326 | (actuator) |

Alternatively, if actuator is requested to be factory mounted, order:

| Item 1 VG82G1S1N | (valve body) |
| :--- | :--- |
| Item 2 RA-3041-7326+M | (actuator) |

Accessory Kits for field mounting

| EQ-5687-7011 | Two Auxiliary Switches and <br> Feedback Potentiometer 2 k $\Omega$ |
| :--- | :--- |
| $\mathbf{2 8 2 ~ 3 5 0 1 ~ 1 1 4 ~}$ | Cable conduit adapter PG 13.5 <br> $(\varnothing 7 \ldots 11 \mathrm{~mm})$ DIN 46320 - FS |

Repair parts

| EQ-0572-7041 | Electronic Positioner EPOS 7 <br> plug-in module for field <br> replacement |
| :--- | :--- |

## Actuator - Valve combinations

The RA-3000 electric actuators are specifically designed to be used in conjunction with the VBB, VBD, VBF and VG8000N valve series. The ordering data for these valve bodies are as follows:

- VBB series (PN 16 and 25 pressure balanced flanged valves)
2-way PDTC DN 50... 150
- VBD series (PN 25 flanged valves)

2-way PDTC DN 15... 150
3-way mixing DN 15... 150

- VBF series (PN 6 \& PN 10 flanged valves)

2-way PDTO DN 65... 100
3-way mixing DN 65... 100

- VG8000N series (PN16 flanged valves)

| 2-way PDTC | DN 15... 150 |
| :--- | :--- |
| 2-way PDTO | DN 15... 40 |
| 3-way mixing | DN 15..150 |
| 3-way diverting | DN 15... 150 |

- VG8000V series (PN16 flanged valves Max fluid temperature $140^{\circ} \mathrm{C}$ )
2-way PDTC
DN 15... 150
3 -way mixing
DN 15... 150
- VG9000 series (PN 6 \& PN 10 flanged valves)
$\begin{array}{ll}\text { 2-way PDTO } & \text { DN } 80 \& 100 \\ \text { 3-way mixing } & \text { DN } 80 \& 100\end{array}$
3-way mixing DN 80 \& 100

Please refer to the relevant flanged valve product bulletins for complete ordering information.

## Operation

## 3-point models

| Connections | Actuator Stem |
| :---: | :---: |
| $1-2$ | extends |
| $1-3$ | retracts |

## Proportional models

| Action Jumper | Input control <br> signal | Actuator <br> Stem |
| :---: | :---: | :---: |
| Direct acting | increases | retracts |
| (DA) | decreases | extends |
| Reverse acting | increases | extends |
| (RA) | decreases | retracts |

## M/ounting instructions

When mounting the actuator on a valve, please follow the instructions below:

- It is recommended that the valves be mounted in the upright position in a conveniently accessible location. When mounted horizontally, the yoke should be fitted such that the stanchions are positioned vertically one above the other.

- The actuator must be protected against dripping water, which could enter the housing and damage the mechanism or motor.
- The actuator must not be covered with insulating material
- Sufficient clearance must be allowed for actuator removal (refer to the dimension drawings)
- The valve must be fitted so that the plug seats against the flow as indicated by the arrow(s) on the valve body.


## $W_{\text {iring instructions }}$

- All wiring must be in accordance with local regulations and national electrical codes, and should be carried out by authorised personnel only.
- Make sure that the line power supply is in accordance with the power supply specified on the device.
- See also the instructions in paragraph "Application".


## ! WARNING

## Shock Hazard

Disconnect the power supply before wiring connections are made to avoid personal injury.

## Equipment Damage Hazard

Make and check all wiring connections before applying power to the system. Short circuited or improperly connected wires may result in permanent damage to the unit

## Wiring diagrams

## 3-point models



Proportional models


## Adjustments

## ! warning <br> Shock Hazard

The utmost care must be taken when the cover is removed (by authorised personnel only) for adjustment or inspection.
In all other cases when the cover is removed the power must be switched off.

Do not touch or attempt to connect or disconnect wires when the electrical power is on.

## Switch S7

The electrical supply can be switched off manually by pressing the red button on the underside of the motor unit housing. When power is off it protrudes 5 mm , with power on, it protrudes 2 mm .


Hand crank (optional) enables manual positioning of the valve. The power supply should be switched off by means of switch S7 before the hand crank is used.

## Actuators with $0 . . .10$ V DC Positioner

Models with built-in electronic positioner have a $0 . .10 \mathrm{~V}$ input. The starting point, the span and the D.A. or R.A. (Direct or Reverse Action) mode can be adjusted on the positioner.


## Applications

Parallel and sequenced operation of actuators

## ! CAUTION

Parallel connection is only possible using isolation relays. If the parallel running motors do not have separately switched power supplies one or more motors will start to cycle at the end of travel.

## Actuators ( 24 V only) with built-in positioner for controllers with $0 . . .10 \mathrm{~V}$ output



The controller output $0 \ldots 10 \mathrm{~V}$ can operate several actuators with built-in electronic positioner EPOS. The electrical wiring for parallel and sequenced operation is identical. The sequencing and action of the actuator are individually adjustable on each positioner. Each positioner has its own adjustment for starting point between $0 \ldots 10 \vee(0 \ldots 100 \%)$ and span between $2 \ldots 10 \mathrm{~V}$ (20... $100 \%$ ). Using the minimum adjustable span of $20 \%$ therefore enables a maximum of 5 sequenced devices; further sequencing can be accomplished by using additional controller outputs. Each positioner can be switched for direct or reverse action.


Adjustments for Y1, Y2, Y3 (example):

|  | starting point | span | positioner action |
| :--- | :---: | :---: | :--- |
| Y1 | $0 \%$ | $30 \%$ | reverse acting |
| Y2 | $35 \%$ | $25 \%$ | reverse acting |
| Y3 | $70 \%$ | $30 \%$ | direct acting |

## Reversible actuator without positioner for incremental controller

## Sequencing two actuators without

 positioner using limit switches

## Parallel operation of actuators without positioner with synchronous motor, condenser and limit switches

Although synchronous motors have the same running speed (rate of travel) deviation in travel between motors can accumulate during starts and stops because of varying load. This deviation depends on the number of on/off cycles and is about 0.5 \% per 100 cycles. By periodical switching of the actuators to end of travel (e.g. normal position) parallel-operated actuators can run reasonably synchronous.

Dimensions in mm


1x PG13,5 (for cable ø7... 11 mm )
+1 blanking plug

|  | RA-3xxx -712x | RA-3xxx -722x | RA-3xxx -732x |
| :---: | :---: | :---: | :---: |
| H1 | 58 mm | 66 mm | 66 mm |

## $S_{\text {pecifications }}$

| Actuator models | RA-3xxx-.... |  |  |
| :---: | :---: | :---: | :---: |
|  | -712x | -722x | -732x |
| Associated valve series and body sizes |  | VBB DN 5065 | VBB DN 80150 |
|  | VBD DN 15... 40 | VBD DN 5065 | VBD DN 50150 |
|  |  | VBF DN 65... 100 | VBF DN 65... 100 |
|  | VG8000N DN 15... 40 | VG8000N DN 50... 80 | VG8000N DN 50... 150 |
|  | VG8000V DN 15... 40 | VG8000V DN 50... 80 | VG8000V DN 50... 150 |
|  |  | VG9000 DN 80 \& 100 | VG9000 DN 80 \& 100 |
| Type of motor |  | Synchronous, Reversible |  |
| Action / Control - 3-point <br> 3-point with 5(3) A / 250 VAC auxiliary switches and $2 \mathrm{k} \Omega$ or $135 \Omega$ feedback potentiometer <br> Proportional with built-in $0 . .10 \mathrm{~V}$ electronic positioner (input impedan $5.6 \mathrm{k} \Omega$ ) and with 5(3) A / 250 VAC auxiliary switches |  |  |  |
| Hand crank |  | Optional |  |
| Supply voltage and frequency*) | $\begin{aligned} & 24 \mathrm{VAC} \pm 10 \%, 50 / 60 \mathrm{~Hz} \\ & 230 \mathrm{VAC} \pm 10 \%, 50 / 60 \mathrm{~Hz} \end{aligned}$ | $\begin{aligned} & 24 \mathrm{VAC} \pm 10 \%, 50 / 60 \mathrm{~Hz} \\ & 230 \mathrm{VAC} \pm 10 \%, 50 / 60 \mathrm{~Hz} \end{aligned}$ | $\begin{gathered} 24 \mathrm{VAC} \pm 10 \%, 50 / 60 \mathrm{~Hz} \\ 230 \mathrm{VAC} \pm 10 \%, 50 / 60 \end{gathered}$ |
| Power consumption (with positioner) | $\begin{gathered} \hline 7 \mathrm{VA} \\ (9 \mathrm{VA}) \\ \hline \end{gathered}$ | $\begin{gathered} 10 \mathrm{VA} \\ (12 \mathrm{VA}) \end{gathered}$ | $\begin{gathered} 16 \mathrm{VA} \\ (18 \mathrm{VA}) \\ \hline \end{gathered}$ |
| Nominal force | 1600 N | 1800 N | 3000 N |
| Nominal stroke | 13 mm | 25 mm | 42 mm |
| Nominal running speed at $50(60) \mathrm{Hz}$ | 6.24 ( 5.20 ) s/mm | 4.16 ( 3.48 ) s/mm | 4.4 ( 3.67 ) s/mm |
| Enclosure Protection | IP 54 |  |  |
| Materials: Stem Motor unit housing and Yoke | Stainless steel (DIN Mat. spec. No. 1.4305 ) Die cast aluminium |  |  |
| Operation and Storage Conditions | $\begin{gathered} -10 \ldots+60^{\circ} \mathrm{C} \\ \left(-10 \ldots+50^{\circ} \mathrm{C}\right. \text { with electronic positioner) } \\ \text { R.H. } 10 \ldots 90 \% \text {, non condensing } \end{gathered}$ |  |  |
| Electrical Connection | Threaded connector $2.5 \mathrm{~mm}^{2}$ |  |  |
| Conduit adapter | $1 \times$ PG $13.5+1$ blanking plug |  |  |
| Net weight | 4 kg | 4 kg | 4.4 kg |
| Approvals | European Directives: EMC (89 / 336 / EEC) LVD (73 / 23 / EEC) |  |  |

[^0]The performance specifications are nominal and conform to acceptable industry standards. For application at conditions beyond these specifications, consult the local Johnson Controls office. Johnson Controls, Inc. are not liable for damages resulting from misapplication or misuse of its products.

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Headquarters: Milwaukee, Wisconsin, USA
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[^0]:    ${ }^{*}$ ) For other supply voltage and frequency, please contact your Johnson Controls supplier.

